# CS412: Lecture #22

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## April 14, 2015

# Simpson's rule

This is a slightly more complicated algorithm, but the accuracy gains are so attractive that it has become somewhat of a golden standard for numerical integration. It is based on (piecewise) *quadratic* interpolation. Specifically, consider three equally spaced x-values:

 $x_1, x_2 = x_1 + h, x_3 = x_1 + 2h$ 

with associated y-values,  $y_i = f(x_i)$ , i = 1, 2, 3. We will approximate f(x) in  $[x_1, x_3]$  with a quadratic  $p(x) = c_2 x^2 + c_1 x + c_0$  that interpolates the three data points  $(x_1, y_1)$ ,  $(x_2, y_2)$ ,  $(x_3, y_3)$ . Using Lagrange interpolation:

$$l_1(x) = \frac{(x-x_2)(x-x_3)}{(x_1-x_2)(x_1-x_3)} = \frac{(x-x_2)(x-x_3)}{(-h)(-2h)} = \frac{1}{2h^2}(x-x_2)(x-x_3)$$

$$l_2(x) = \frac{(x-x_1)(x-x_3)}{(x_2-x_1)(x_2-x_3)} = -\frac{1}{h^2}(x-x_1)(x-x_3)$$

$$l_3(x) = \frac{(x-x_1)(x-x_2)}{(x_3-x_1)(x_3-x_2)} = \frac{1}{2h^2}(x-x_1)(x-x_2)$$

and  $p(x) = y_1 l_1(x) + y_2 l_2(x) + y_3 l_3(x)$ . We then proceed to approximate

$$\underbrace{\int_{x_1}^{x_3} f(x)dx}_{I} \approx \underbrace{\int_{x_1}^{x_3} p(x)dx}_{I_{\text{simp}}} = \sum_{i=1}^3 y_l \int_{x_1}^{x_3} l_i(x)dx$$

After some easy (yet tedious) analytic integration using the previous formulas, we get:

$$\int_{x_1}^{x_3} l_1(x) dx = \frac{h}{3}, \int_{x_1}^{x_3} l_2(x) dx = \frac{4h}{3}, \int_{x_1}^{x_3} l_3(x) dx = \frac{h}{3}$$

Thus,

$$\int_{x_1}^{x_3} p(x)dx = \frac{h}{3}(f(x_1) + 4f(x_2) + f(x_3))$$

This is Simpson's rule and is commonly written as:

$$\int_{a}^{b} f(x)dx \approx \underbrace{\overbrace{b-a}^{=2h}}_{6} \left[ f(a) + 4f\left(\frac{a+b}{2}\right) + f(b) \right]$$

In order to define the respective composite rule, we use a partitioning:

 $a = x_0 < x_1 < x_2 < \ldots < x_{2n-1} < x_{2n} = b$ 

This time we define each interval  $D_k = [x_{2k}, x_{2k+2}]$ , and

$$I_{k} = \int_{x_{2k}}^{x_{2k+2}} f(x) dx \Rightarrow I = \sum_{k=0}^{n-1} I_{k}$$

Then,

$$I_{k,\mathsf{simp}} = \frac{h}{3} [f(x_{2k}) + 4f(x_{2k+1}) + f(x_{2k+2})]$$

and the composite rule  $I_{simp} = \sum_{k=0}^{n-1} I_{k,simp}$  becomes:

$$I_{simp} = \frac{h}{3} [f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + 2f(x_4) + \ldots + 2f(x_{2n-2}) + 4f(x_{2n-1}) + f(x_{2n})]$$

In order to estimate the local error, we again try to use the formula for the interpolation error of passing a quadratic  $p^{(k)}(x)$  through  $(x_{2k}, f(x_{2k})), (x_{2k+1}, f(x_{2k+1})), (x_{2k+2}, f(x_{2k+2}))$ .

$$f(x) - p^{(k)}(x) = \frac{f^{(3)}(c_k)}{3!}(x - x_{2k})(x - x_{2k+1})(x - x_{2k+2})$$

Thus,

$$e_{k} = \left| \int_{x_{2k}}^{x_{2k+2}} [f(x) - p(x)] dx \right|$$

$$\leq \int_{x_{2k}}^{x_{2k+2}} \frac{|f^{(3)}(c_{k})|}{3!} |(x - x_{2k})(x - x_{2k+1})(x - x_{2k+2})| dx$$

$$\leq \frac{1}{6} ||f^{(3)}||_{\infty} \int_{x_{2k}}^{x_{2k+2}} |\underbrace{(x - x_{2k})(x - x_{2k+1})(x - x_{2k+2})}_{(\star)} |dx|$$

And with this we are at a dead end! We cannot simply remove the absolute value in the expression  $(\star)$  since it changes sign in  $[x_{2k}, x_{2k+2}]$ . Even if we break up this integral in sub-intervals, we will *at best* show that Simpson's rule is 3rd order accurate, where in fact it is even *more*, i.e., 4th order accurate!

To achieve our goal, we will use a different (and more general) type of analysis. It is possible to show that:

**Theorem 1.** If an integration rule integrates exactly any polynomial up to degree (d-1), then the global error is  $O(h^d)$  or better, i.e., the rule is at least *d*-order accurate.

**Methodology:** We will test Simpson's rule on monomials  $f(x) = x^d$ , d = 0, 1, 2, ...

• 
$$f(x) = 1$$
:

$$I_{\mathsf{simp}} = \frac{b-a}{6}[1+4+1] = (b-a) \equiv \int_a^b 1 \cdot dx \Rightarrow \mathsf{correct!}$$

• f(x) = x:

$$I_{\mathsf{simp}} = \frac{b-a}{6} \left[ a + 4f\left(\frac{a+b}{2}\right) + b \right] = \frac{b^2}{2} - \frac{a^2}{2} \equiv \int_a^b x dx \Rightarrow \mathsf{correct!}$$

• 
$$f(x) = x^2$$
:  
 $I_{simp} = \frac{b-a}{6} \left[ a^2 + f\left(\frac{a+b}{2}\right)^2 + b^2 \right] = \frac{b^3}{3} - \frac{a^3}{3} \equiv \int_a^b x^2 dx \Rightarrow \text{correct!}$ 

• 
$$f(x) = x^3$$
:  
 $I_{simp} = \frac{b-a}{6} \left[ a^3 + 4 \left( \frac{a+b}{2} \right)^3 + b^3 \right] = \frac{b^4}{4} - \frac{a^4}{4} \equiv \int_a^b x^3 dx \Rightarrow \text{correct!}$ 

•  $f(x) = x^4$ :  $I_{simp} = \frac{b-a}{6} \left[ a^4 + 4 \left( \frac{a+b}{2} \right)^4 + b^4 \right]$ 

which is not equal to  $\frac{b^5}{5} - \frac{a^5}{5} = \int_a^b x^4 dx$ 

Thus, Simpson's rule is 4th order accurate, i.e.,

$$e_{k,\text{local}} \le O(h^5)$$
  
 $e_{k,\text{global}} \le O(h^4)$ 

### Assessing order of accuracy in integration rules

**Theorem 2.** If an integration rule integrates exactly any polynomial up to degree (d-1), then the global error is  $O(h^d)$  or better, i.e., the rule is at least *d*-order accurate.

#### Methodology:

- Test the integration rule on *monomials* of degree  $0, 1, 2, \ldots$ , i.e., on f(x) = 1, f(x) = x,  $f(x) = x^2, \ldots$
- If  $f(x) = x^d$  is the 1st test function that is *not* integrated exactly, the order of accuracy is *equal* to *d*.

**Example:** Trapezoidal rule  $I = \int_a^b f(x) dx \approx \frac{f(a) + f(b)}{2} (b - a).$ 

• f(x) = 1:

$$I_{\mathsf{trap}} = \frac{1+1}{2}(b-a) = (b-a) \Rightarrow \mathsf{exact!}$$

• f(x) = x:

$$I_{\rm trap} = \frac{a+b}{2}(b-a) = \frac{b^2}{2} - \frac{a^2}{2} \Rightarrow {\rm exact}!$$

• 
$$f(x) = x^2$$
:

$$I_{\text{trap}} = \frac{a^2 + b^2}{2}(b-a) \xrightarrow{\text{not exact}} \left( \int_a^b x^2 dx = \frac{b^3}{3} - \frac{a^3}{3} \right)$$

Thus, trapezoidal rule is 2nd order accurate!